



Large Type **TRX-L**

Compact Type **TRX-S**

Features 1 **Human hand shaped three finger linkage system**

Human hand design allows one to grasp objects of various size and shape. The shape looks like a human hand, so you can intuitively understand how it grasps the object.

Features 2 **All-in-one**

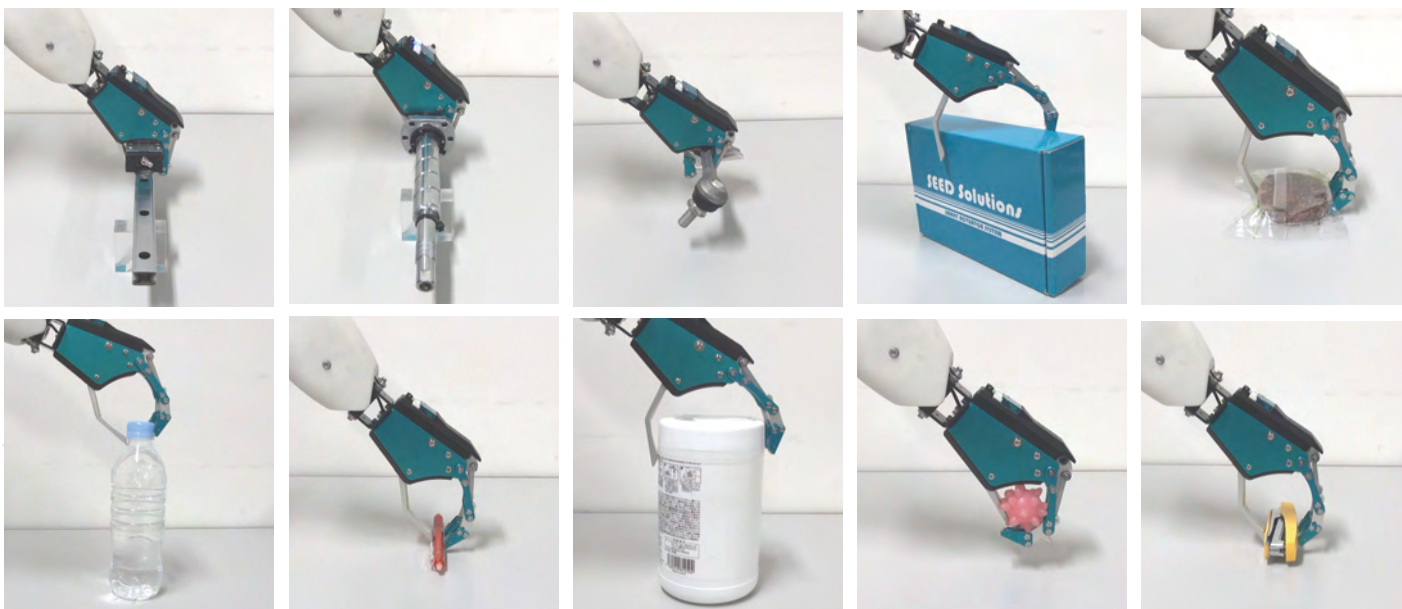
It contributes to space saving by integrating fingers, actuator, and the driver controller.

Features 3 **Lightweight**

A compact type TRX-S achieves weight of 320g. Making a robot hand lighter allows a heavier object to be transferred when used on a robot arm.

Model No.	TRX-S	TRX-L
Maximum gripping diameter [mm]	100	150
Maximum pinching force [N]	10	40
Maximum gripping force [N] *	40	150
Weight [g]	320	1200
Power supply voltage [V]	24	

■ **Example of gripping / pinching Operation**



* The gripping force may decrease depending on object size.

